

# SHIFTLEFT

Maintainer insight | Risk Quantification

## **CPARTA**

- Developing and enabling a Swedish Commercial Cyber Defense
- Protect Swedish Critical Infrastructure and Critical Industry
- Development of Strategic Initiatives and Capabilities

## About Me

- Strategic Coordinator Cparta
- Team Capt. Swedish National Hacking Team
- Vulnerability Research Margin Research



Analysis of motivation and intentions



Quality assurance and compliancy



Weakest link and risk assessment



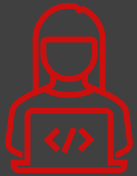
Analysis of motivation and intentions



Contributor metadata analysis & code analysis

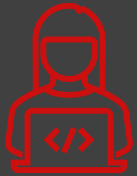


Contributor metadata  
analysis





Contributor metadata  
analysis & code analysis





Contributor metadata  
analysis & code analysis

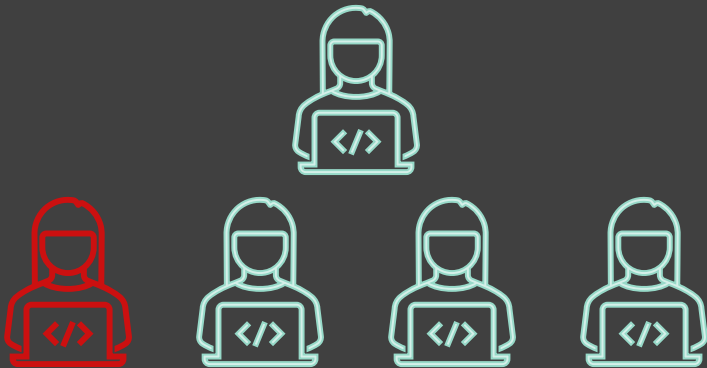


By which metrics do  
we quantify code  
quality?



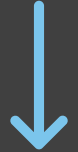


SHIFTLEFT Maintainer  
overview of contributors



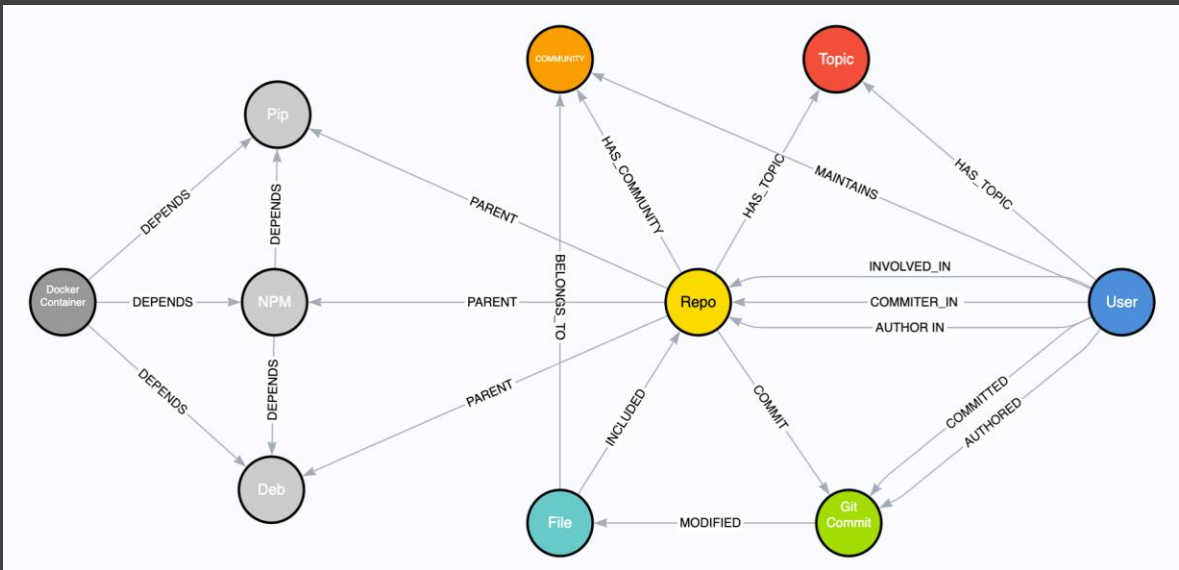
```
9a640e3 | Pillow / libImaging / Convert.c | Top
Code | Blame | 1132 lines (961 loc) · 26.1 KB | Raw | Copy | Download | Edit | View
1068         convert = converters[sty].convert,
1069         break;
1070     }
1071
1072     if (!convert)
1073 #ifdef notdef
1074         return (Imaging) ImagingError_ValueError("conversion not supported");
1075 #else
1076     {
1077         static char buf[256];
1078         /* FIXME: may overflow if mode is too large */
1079         sprintf(buf, "conversion from %s to %s not supported", imIn->mode, mode);
1080         return (Imaging) ImagingError_ValueError(buf);
1081     }
1082 #endif
1083
1084     imOut = ImagingNew2(mode, imOut, imIn);
1085     if (!imOut)
1086         return NULL;
1087
1088     ImagingSectionEnter(&cookie);
1089     for (y = 0; y < imIn->ysize; y++)
1090         (*convert)((UINT8*) imOut->image[y], (UINT8*) imIn->image[y],
1091                 imIn->xsize);
1092     ImagingSectionLeave(&cookie);
1093
1094     return imOut;
1095 }
```

# django



C code from 1997  
With critical FIXMEs

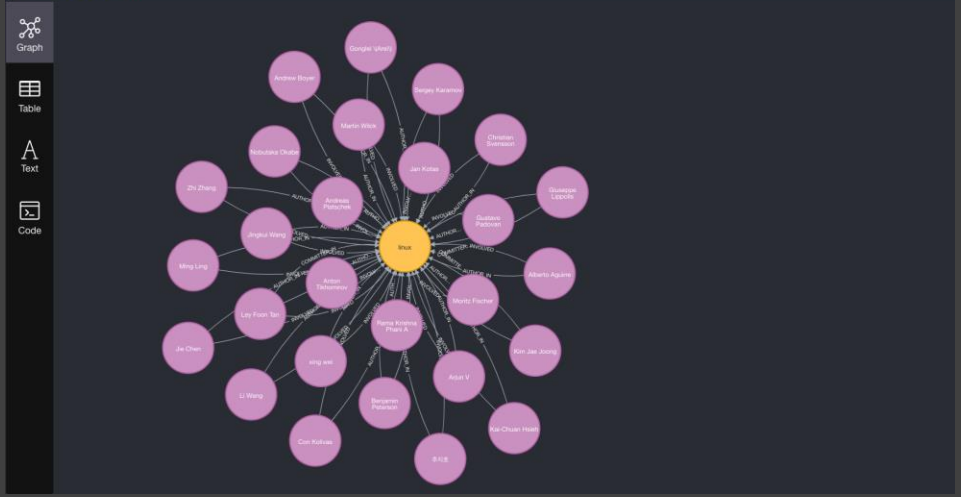
# Reagent – Margin Research



```

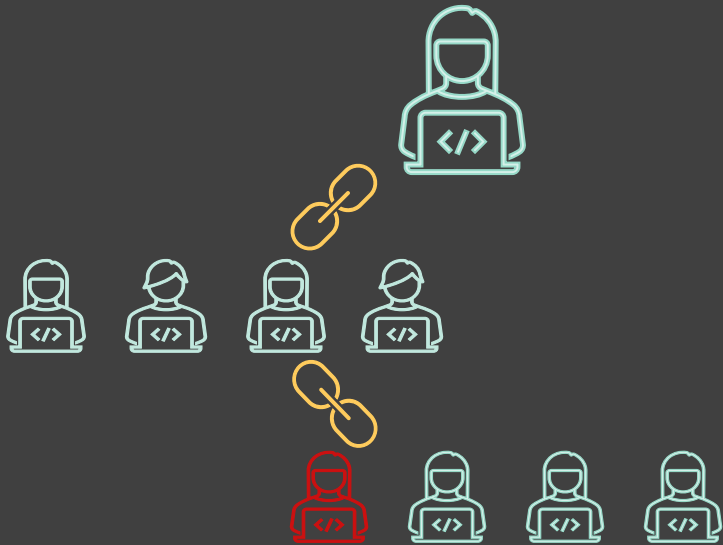
1 MATCH (r:Repo {full_name: 'torvalds/linux'})-[:AUTHOR_IN | COMMITTER_IN]-(u:User)
2 RETURN r, u
3 LIMIT 30

```



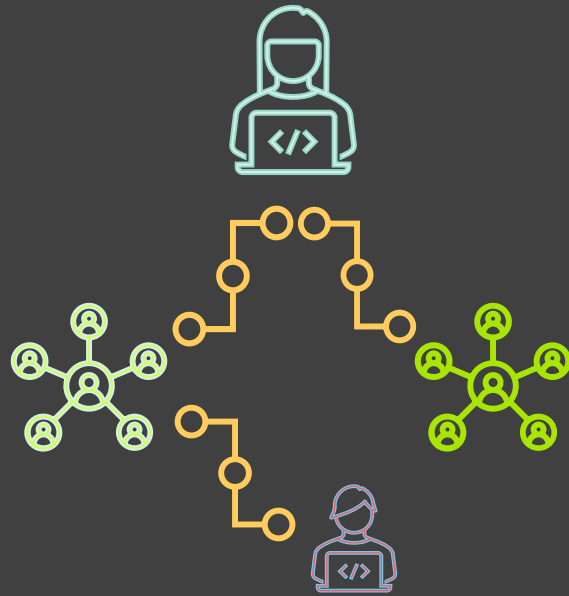


# SHIFTLEFT Maintainer overview of dependencies



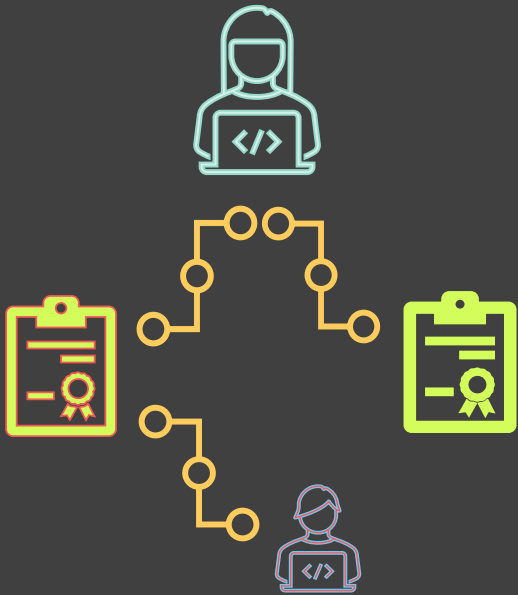


# SHIFTLEFT Maintainer Weakest Link Risk identification





## SHIFTLEFT Maintainer Continuous Quality & Risk Report





Metrics of "good" code &  
Metrics of "trusted" contributor



- Issues generated / LoC (vulnerability does not require malicious intent)
- AI code quality assessment (Lack of maintenance)
- Graph based contribution analysis (Behaviour & Intent)



Metrics of "good" code &  
Metrics of "trusted" contributor



- Bug transmission project-to-project adoption
  - e.g. Glibc stealing Musl code with bugs in them
- AI analysis of "Does this commit only solve the issue?"
  - Hidden introductions of features / vulnerabilities
- Analysis of "Does this code alter the scope of access"
  - Accessing new resources



```
/*- Read comments from end of lifetime to start of lifetime. *-
```

```
// Usage implies proof is necessary: assert N <= direction <= E
void foobar(enum Direction direction) {
    switch (direction) {
        case N: ...
        case W: ...
        case E: ...
        // switch case has holes in enumeration coverage. Proof state: assert N <= direction <= E
    }
    // End of lifetime of direction.
}
```

```
void karbar() {
    // Bug is found since there exists no proof for assert N <= direction
    // end of life for direction, sink point in syscall assumes no bounding

    enum Direction direction = ... // user input

    // Proof state: assert N <= direction

    if (direction <= E) { System.exit(0); }
    // Code path not reachable for direction > E. Satisfies iff assert N <= direction

    foobar(direction) // on call-site needs to prove: "assert N <= direction <= E"
}
```

Lean proof state – challenge to communicate to maintainer. Needs to be intuitive

```
n : ℕ
s : ℕ → ℝ
h1 : n > 2
h2 : attainable n s
h1' : 2 < ↑n
⊢ 0 < ↑n - 3
```

▼ Messages (1)

▼ prev\_bound.lean:222:6

linarith failed to find a contradiction

▼ case h

```
n : ℕ
s : ℕ → ℝ
h1 : n > 2
h2 : attainable n s
h1' : 2 < ↑n
at : 0 ≥ ↑n - 3
⊢ False
```

- Imperial College London teaching lean for formal proofs
- Integrating formal proofs in to language design
  - In an intuitive way using AlphaProof et.c
- Theorem proving is already a part of industry
  - PLC industrial systems
  - Proof of soundness for cryptocurrencies (Zellic et al.)

**Questions?**